

Adjacency matrices of complex unit gain graphs

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August 21, 2020

Outline

- Adjacency matrices of graphs
- Spectral properties
- Perron-Frobenius theorem
- Adjacency matrices of complex unit gain graphs
- Characterization of bipartite graphs and trees

Adjacency matrix

Definition (Adjacency matrix)

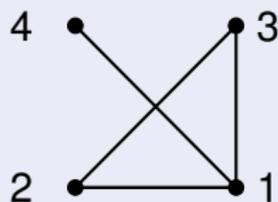
The adjacency matrix of a graph G with n vertices, $V(G) = \{v_1, \dots, v_n\}$ is the $n \times n$ matrix, denoted by $A(G) = (a_{ij})$, is defined by

$$a_{ij} = \begin{cases} 1 & \text{if } v_i \sim v_j, \\ 0 & \text{otherwise.} \end{cases}$$

Example

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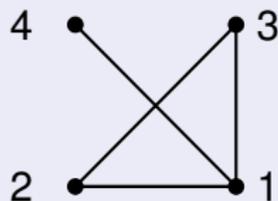
Consider the graph G



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The **adjacency matrix** of G is

$$A(G) = \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

Properties

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- 1 A is symmetric.
- 2 Sum of the 2×2 principal minors of A equals to $-|E(G)|$.
- 3 $(i, j)^{th}$ entry of the matrix A^k equals the number of walks of length k from the vertex i to the vertex j .

Spectrum of adjacency matrix

Let G be a graph with n vertices and with eigenvalues of its adjacency matrices, $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$. We denote by $\Delta(G)$ and $\delta(G)$, the maximum and the minimum of the vertex degrees of G , respectively.

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Irreducible matrices

An $n \times n$ matrix, $n \geq 2$, is *reducible* if its rows and columns can be simultaneously permuted to

$$\begin{pmatrix} B & C \\ 0 & D \end{pmatrix}$$

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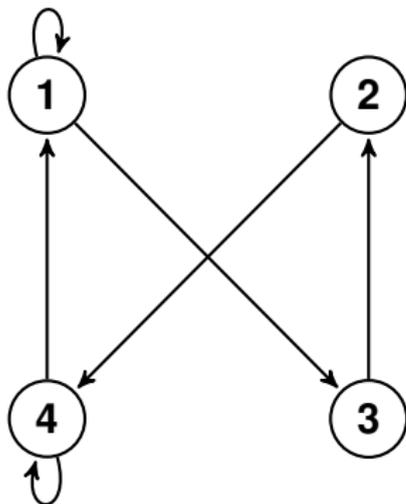
Working definition: A is irreducible if and only if $G(A)$ is strongly connected.

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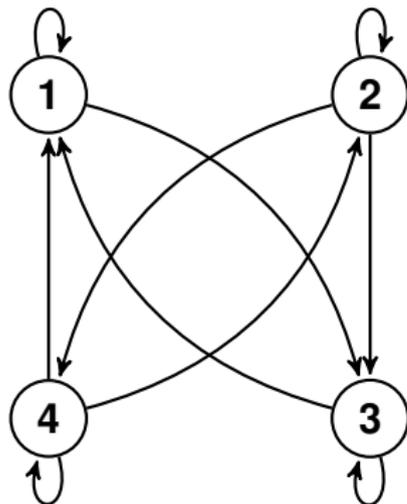


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Perron-Frobenius Theorem

Theorem

If A is nonnegative and irreducible, then

- a) $\rho(A) > 0$, where $\rho(A)$ is the maximum of absolute value of all the eigenvalues of A ,
- b) $\rho(A)$ is an eigenvalue of A ,
- c) *There is a positive vector such that $Ax = \rho(A)x$.*

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Let $A, B \in \mathbb{C}^{n \times n}$ and suppose that A is nonnegative. If $A \geq |B|$, then $\rho(A) \geq \rho(|B|) \geq \rho(B)$.

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Gain graphs

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- The directed edge set $\overrightarrow{E(G)}$ consists of the directed edges $e_{jk}, e_{kj} \in \overrightarrow{E(G)}$, for each adjacent vertices j and k of G .
- Assign a weight (gain) $g \in \mathcal{G}$ for each directed edge $e_{jk} \in \overrightarrow{E(G)}$, such that the weight of e_{kj} is g^{-1} . Let us denote this assignment by φ .

\mathbb{T} -gain adjacency matrix

Definition (Thomas Zaslavsky)

A **\mathbb{G} -gain graph** is a graph G in which each orientation of an edge is given a gain which is the inverse of the gain assigned to the opposite orientation.

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- $\mathcal{G} = \{\pm 1, \pm i\}$ [D. Kalita and S. Pati(2014)] ,
- $\mathcal{G} = \{1, \pm i\}$ [K. Guo and B. Mohar(2017), J. Liu and X. Li(2015)],
- $\mathcal{G} = \{1, \frac{1 \pm i\sqrt{3}}{2}\}$. [B. Mohar(2020)]
- $\mathcal{G} = \{1, e^{\pm i\theta}\}$, $\theta \in \mathbb{R}$. [S. Kubota, E. Segawa and T. Taniguchi(2019)]
- $\mathcal{G} = \mathbb{C}^*$ (with nonnegative imaginary part)[R. B. Bapat, D. Kalita and S. Pati(2012)].

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$$a_{ij} = \begin{cases} \varphi(\mathbf{e}_{ij}) & \text{if } v_i \sim v_j, \\ 0 & \text{otherwise.} \end{cases}$$

On \mathbb{T} -gain adjacency matrix

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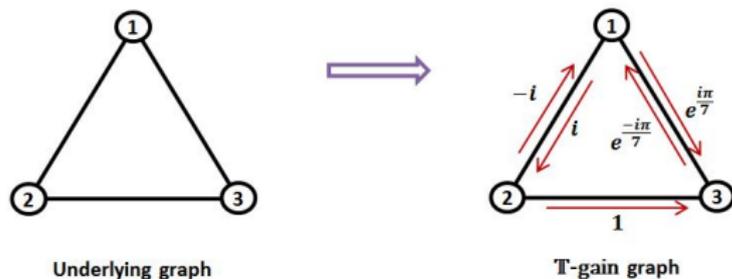


Figure: \mathbb{T} -gain graph Φ and its underlying graph

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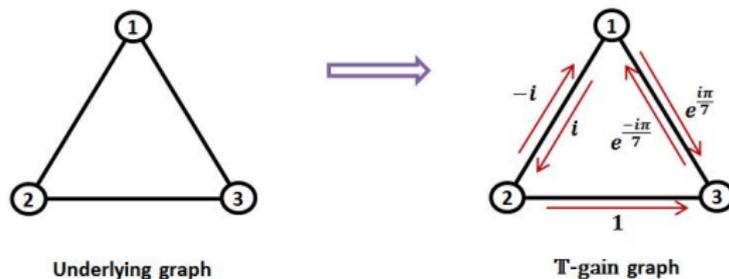


Figure: \mathbb{T} -gain graph Φ and its underlying graph

$$A(\Phi) = \begin{pmatrix} 0 & i & e^{i\frac{\pi}{7}} \\ -i & 0 & 1 \\ e^{-i\frac{\pi}{7}} & 1 & 0 \end{pmatrix}$$

Definition

- **The gain of a cycle** $C = v_1 v_2, \dots, v_l v_1$, denoted by $\varphi(C)$, is defined as the product of the gains of its edges, that is
$$\varphi(C) = \varphi(e_{12})\varphi(e_{23}) \dots \varphi(e_{(l-1)l})\varphi(e_{l1}).$$

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- A function from the vertex set of G to the complex unit circle \mathbb{T} is called a **switching function**.
- We say that, two gain graphs $\Phi_1 = (G, \varphi_1)$ and $\Phi_2 = (G, \varphi_2)$ are said to be **switching equivalent**, written as $\Phi_1 \sim \Phi_2$, if there is a switching function $\zeta : V \rightarrow \mathbb{T}$ such that $\varphi_2(e_{ij}) = \zeta(v_i)^{-1}\varphi_1(e_{ij})\zeta(v_j)$.

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Theorem (Zaslavsky[14],1989)

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Let $\Phi_1 = (G, \varphi_1)$ and $\Phi_2 = (G, \varphi_2)$ be two \mathbb{T} -gain graph. If $\Phi_1 \sim \Phi_2$, then $A(\Phi_1)$ and $A(\Phi_2)$ have the same spectrum.

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Key theorem

Theorem (R. Mehatari, M.-, A. Samanta)

Let $\Phi = (G, \varphi)$ be a \mathbb{T} -gain (connected) graph, then $\rho(A(\Phi)) = \rho(A(G))$ if and only if either Φ or $-\Phi$ is balanced.

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Proof.

(i) Suppose G is bipartite and Φ is balanced. Then due to the absence of odd cycles, $-\Phi$ is balanced.

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- (i) If G is bipartite, then whenever Φ is balanced implies $-\Phi$ is balanced.
- (ii) If Φ is balanced implies $-\Phi$ is balanced for some gain Φ , then the graph is bipartite.

Proof.

(i) Suppose G is bipartite and Φ is balanced. Then due to the absence of odd cycles, $-\Phi$ is balanced.

(ii) Let Φ be a balanced cycle such that $-\Phi$ is balanced. Suppose that G is not bipartite. Then, any odd cycle in G can not be balanced with respect to $-\Phi$, which contradicts the assumption. Thus G must be bipartite. □

Converse of Reff's theorem

Theorem (R. Mehatari, M.-, A. Samanta)

Let $\Phi = (G, \varphi)$ be a \mathbb{T} -gain (connected) graph. Then, $\sigma(A(\Phi)) = \sigma(A(G))$ if and only if Φ is balanced.

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If $\sigma(A(\Phi)) = \sigma(A(G))$, then $\rho(A(\Phi)) = \rho(A(G))$. Now, we have either Φ or $-\Phi$ is balanced. If Φ is balanced, then we are done.

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Characterization of bipartite graphs

Theorem (R. Mehatari, M.-, A. Samanta)

Let G be a connected graph. Then, G is bipartite if and only if $\rho(A(\Phi)) = \rho(A(G))$ implies $\sigma(A(\Phi)) = \sigma(A(G))$ for every gain φ .

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Invariance of gain spectrum and gain spectral radius

Theorem (A.Samanta, M.-)

Let $\Phi = (G, \varphi)$ be a \mathbb{T} -gain graph. Then G is a tree if and only if $\sigma(A(G)) = \sigma(A(\Phi))$ for all φ .

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Let $\Phi = (G, \varphi)$ be a \mathbb{T} -gain graph. TFAE,

- 1 G is tree,
- 2 $\sigma(A(G)) = \sigma(A(\Phi))$ for all φ ,
- 3 $\rho(A(G)) = \rho(A(\Phi))$ for all φ .

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Thank you !