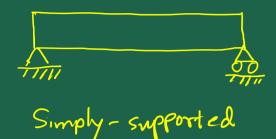
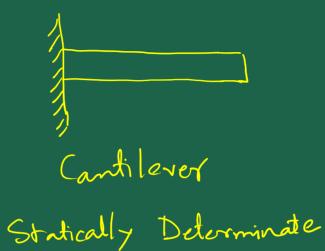
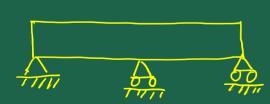
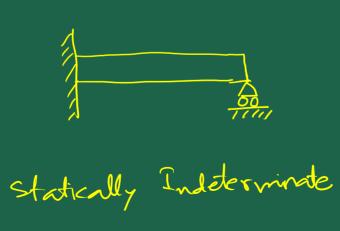
## Bending of Beams

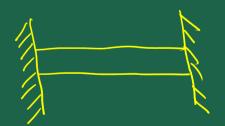


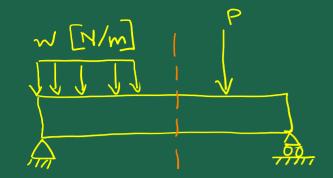












20 > (Shear force)

Ry

(Reading)

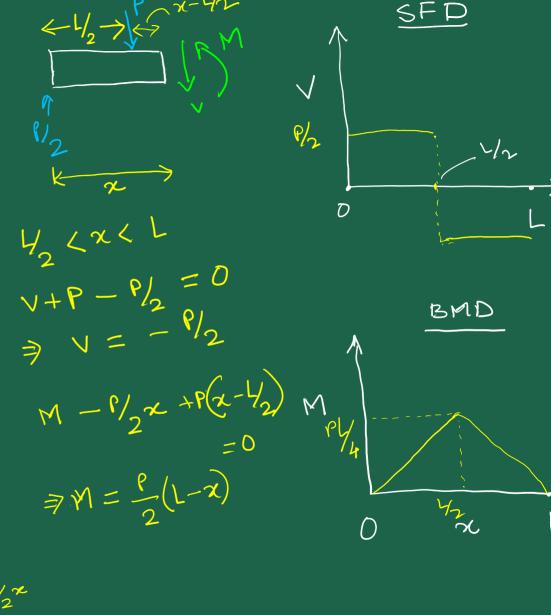
moment)

T Rv2

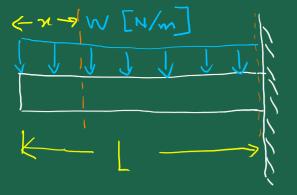
井、

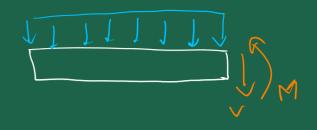
$$|X| = 0$$

$$|X|$$



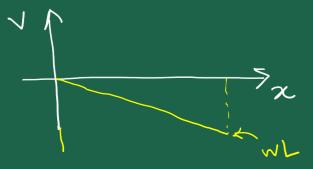
#2





 $\Rightarrow \sum M = 0$ 

1 2 m

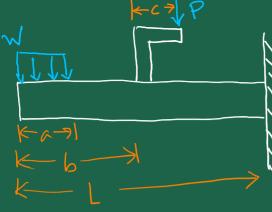


$$\frac{1}{2} + M = 0 \Rightarrow M = -\frac{wx^2}{2}$$

$$\frac{1}{2} + \frac{1}{2} + \frac{1}{2}$$

$$= \frac{1}{2} + \frac{$$

#3



For OX XXA



$$M = -w^2/2$$

K-7-7

you For axxxb

$$V = -wa$$

$$M = -wa\left(x - \frac{a}{2}\right)$$

For bexXL

$$V + P + wa = 0 \Rightarrow V = -wa - P$$

$$M - cP + P(x-b) + wa(x-\frac{a}{2}) = 0$$

$$\frac{1}{2}M = CP - P(x-b) - WA(x-\frac{a}{2})$$

21/3 X W [N/m]

21/3

13/2

13/2

150/2

17/7//

$$\sum M_A = 0$$

$$-\int_{x}^{L}\left(\frac{w}{L}x\right)dx + R_{g}L = 0$$

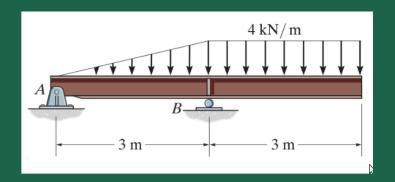
$$\frac{0}{3} = \frac{1}{2} = \frac{1}{3} = \frac{1}{3} = \frac{1}{3}$$

$$\Rightarrow R_{B}L = \left(\frac{WL}{2}\right)\left(\frac{2L}{3}\right)$$

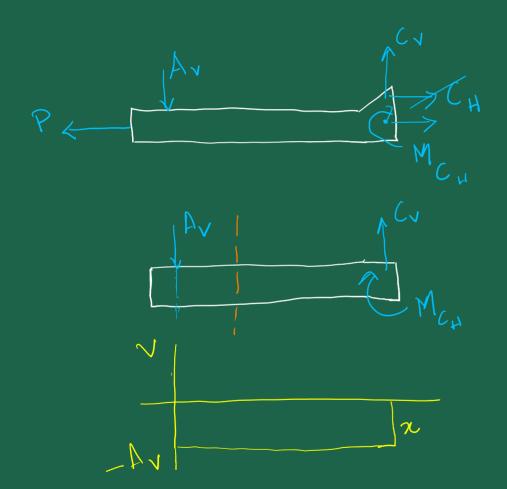
RA dr RE

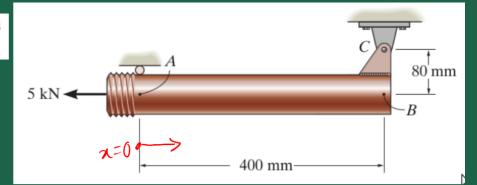
at any pos" x: Wx

3. Draw the shear and moment diagrams for the overhanging beam.



1. Draw the shear force and bending moment diagrams for the pipe. The end screw is subjected to a horizontal force of 5 kN.





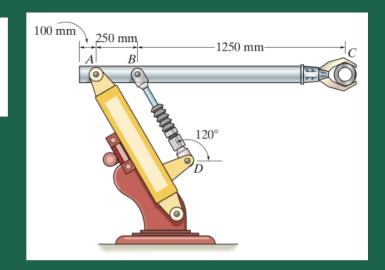
Y +A = 0 => Y = -A y

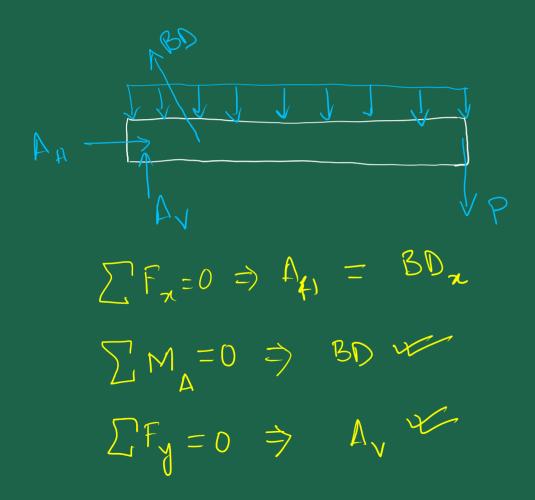
M

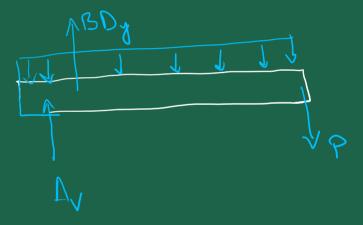
$$\sum F_{y} = O (\uparrow +)$$

$$-V - A_{v} = 0 \Rightarrow V = -A_{v}$$

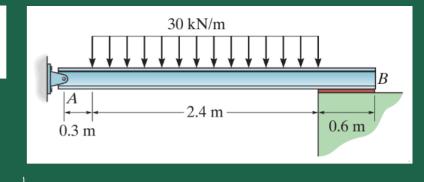
2. The industrial robot is held in the stationary position shown. Draw the shear force and bending moment diagrams of the arm ABC if it is pin connected at A and connected to a hydraulic cylinder (two-force member) BD. Assume the arm and grip have a uniform weight of 0.3 N/mm and support the load of 200 N at C.

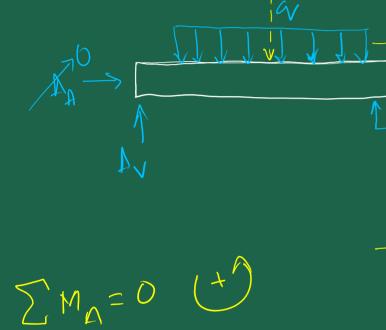






4. The beam is bolted or pinned at A and rests on a bearing pad at B that exerts a uniform distributed loading on the beam over its length of 0.6 m. If the beam supports a uniform loading of 30 kN/m, draw the shear and moment diagrams.





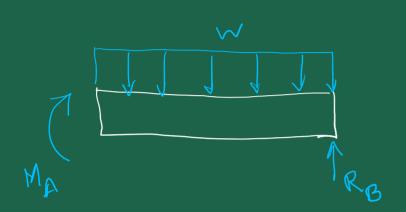
$$(w \times 0.6m) \times 3m = 0 \Rightarrow w$$

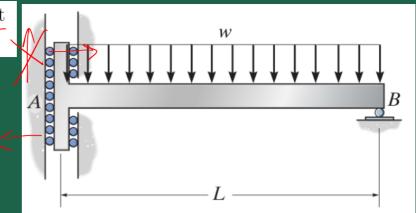
$$\frac{1}{7} - \frac{30 \times N}{m} \times \frac{2.4 \times (.2 + 0.3)}{m} + \frac{(0 \times 0.6)}{m} \times \frac{3}{m} = 0 \Rightarrow 0$$

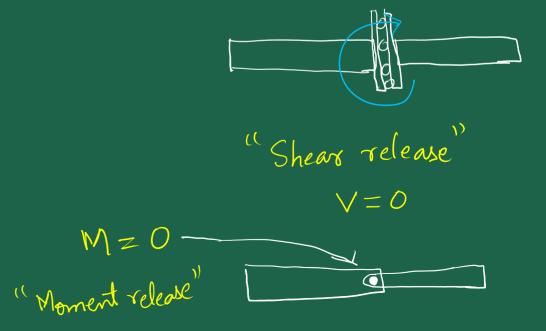
$$\frac{1}{7} = 0 \Rightarrow A_{V} \propto \frac{1}{1}$$



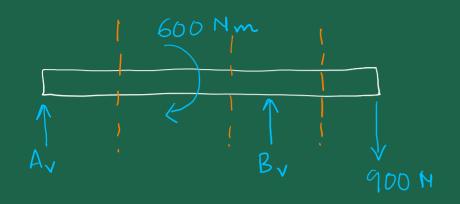
5. Draw the shear and moment diagrams for the beam when the support at A allows it to slide freely along the vertical guide and hence it cannot support a vertical force.







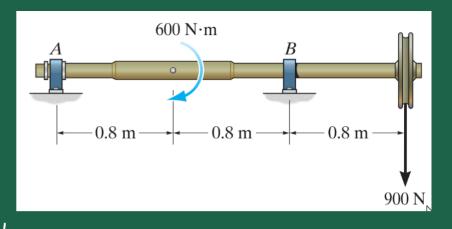
6. The shaft is supported by a smooth thrust bearing at A and a smooth journal bearing at B. Draw the shear and moment diagrams for the shaft.

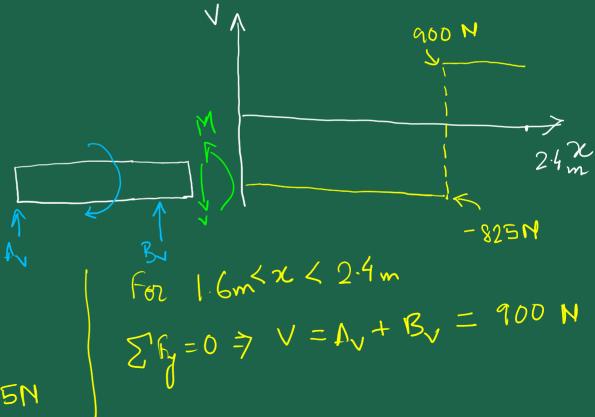


$$\sum_{M_A=0}^{M_A=0} \Rightarrow B_V = 1725N$$

$$\sum_{W_A=0}^{M_A=0} \Rightarrow A_V = -825N$$

$$\sum F_{y}=0 \Rightarrow V-A_{v}=0 \Rightarrow V=A_{v}=-825N$$





For 0< x < 0.8m ( Q x = 0.8m, M = -660 Nm) For 0.8m Lx 2 1.6 m + 2 M=0 > -A,x-600 +M=0 -660 Km > M = 600 + Ayx (@x=0.8m, M=-60 Nm) (@x=1.6m, M=-720 Nm) For 1.6m < x < 2.4m

 $J = 0 = 0 = M - A_{1}x - B_{1}(x - 1.6m) - 600 \text{ Mm} = 0$ 

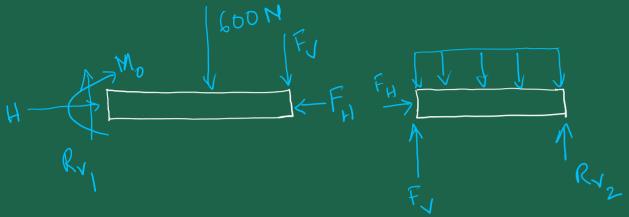
@ x = 1.6m, M= -720Nm

(a x=24m, Mz)

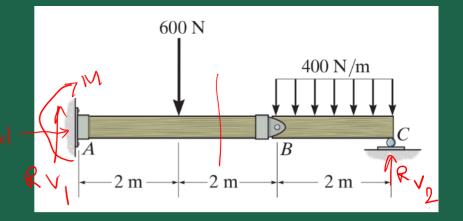
4

8. The compound beam is fixed at A, pin connected at B, and supported by a roller at C. Draw the shear and moment diagrams for the beam.

6 m

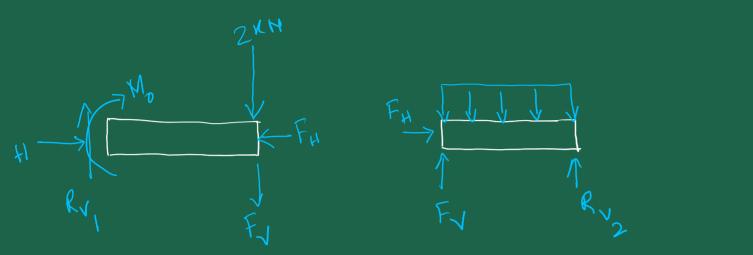




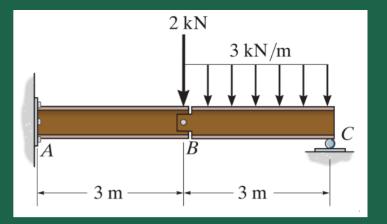




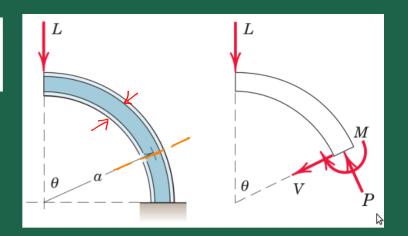
9. The compound beam is fixed at A, pin connected at B, and supported by a roller at C. Draw the shear and moment diagrams for the beam.







11. A curved cantilever beam has the form of a quarter circular arc. Determine the expressions of the shear force V and the bending moment M as functions of  $\theta$ . The depth of the beam is much smaller than the arc radius.



## Relations between load, shear, and bending moment

